

Project 1—Catapult



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Problem Statement

- To launch a standard street hockey ball the longest possible distance using a catapult made of Dow Wallmate extruded polystyrene foam
- The catapult must be assembled from 2 components which must be able to be cut out of a single 23" x 23" x 2" piece of foam.

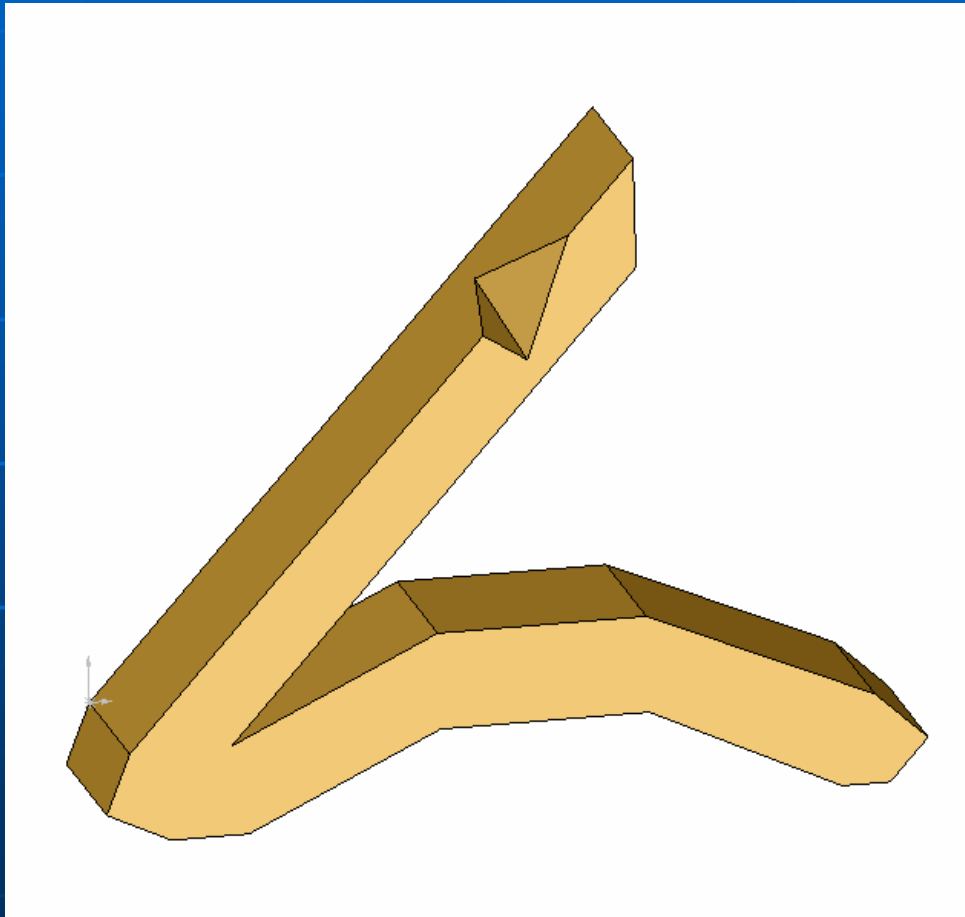
Problem Statement (cont'd)

- The catapult is initially strained by a string attached to a load.
- Two unmodified pencils can also be used to connect the two components and/or transmit the load from string to the catapult.
- The hockey ball is launched by cutting the string, which drops the load and allows the catapult to return to its original position.

Initial Design

- Use both the arm and base to store strain energy
 - 1) Flat base that bends upwards under loading.
 - 2) Curved base that flattens when strained.

Initial Design (cont'd)

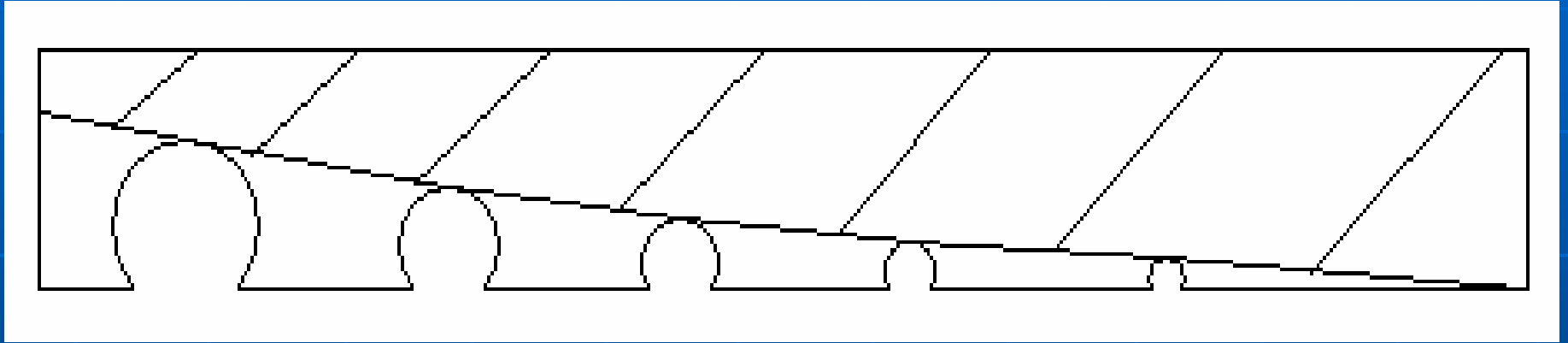


Our first design consisted of two parts like the one shown. The parts were joined by a pencil going through the top of the arm.

Lessons Learned from Competition

- Our initial design was too small and did not take full advantage of the design criteria
- Slot joint is a simpler and more elegant solution to the Clevis joint we used
- An arm designed by a group which used radiuses on the side of compression bent very uniformly

Lessons Learned (cont'd)



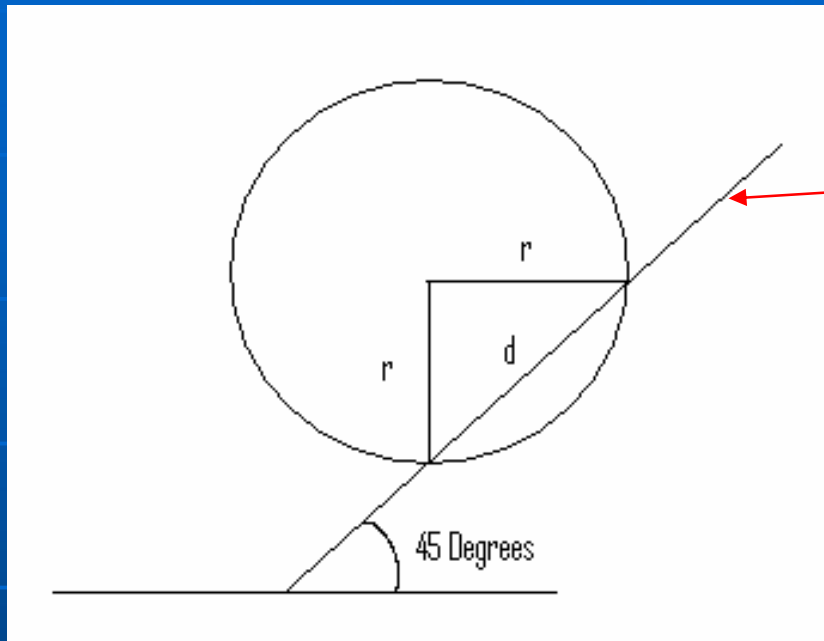
- We came to the conclusion that their performance was not due to the use of radiuses but to the parabolic shape that they approximated.

Approximating a Parabola

- Use straight lines to approximate a parabolic shape
- Substitute in equal increments of x into the following equation to calculate shape of the arm:

$$h_x = h_{\max} \sqrt{\frac{x}{L}}$$

Derivation of Optimal Size of Hole



- Once the angle between the arm and the horizontal is $> 45^\circ$, the centre of gravity of the ball would be outside of the hole.
- Optimal diameter = $\sqrt{2} \times 35mm \cong 50mm$

Optimal Angle between Arm and Base

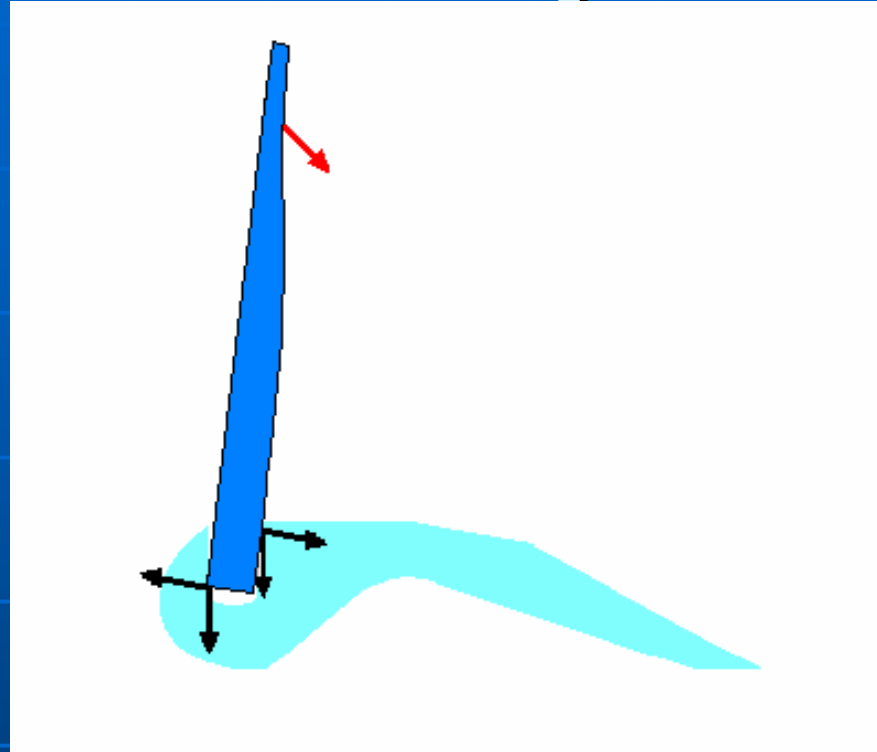
- Used insertion pieces to alter the angle of the arm



Optimal Angle between Arm and Base (cont'd)

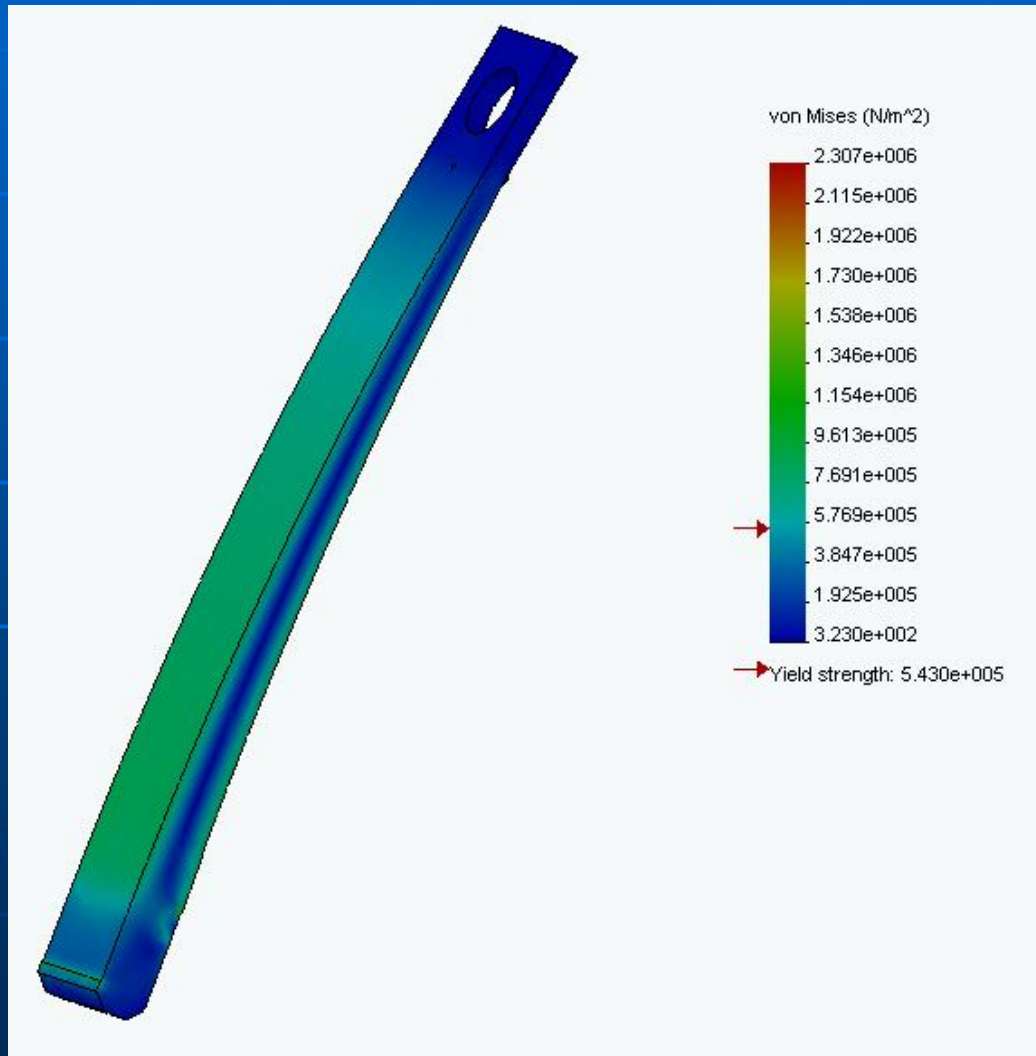
Angle between Arm & Base (degrees)	Distance of Flight (feet)
95	10
90	12
85	9
80	8.5

Mechanics Analysis of Arm



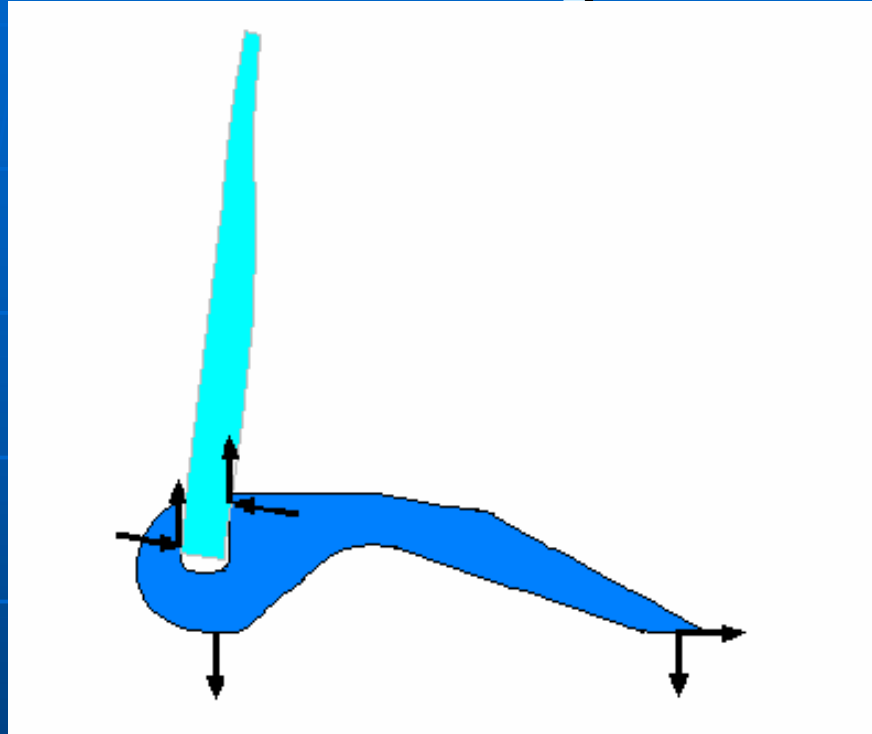
- The force applied by the string (red arrow) can be replaced by two forces located in the contact points shown.
- The torque caused by the string can also be replaced with two forces at the contact points forming a couple.

FEM of Arm



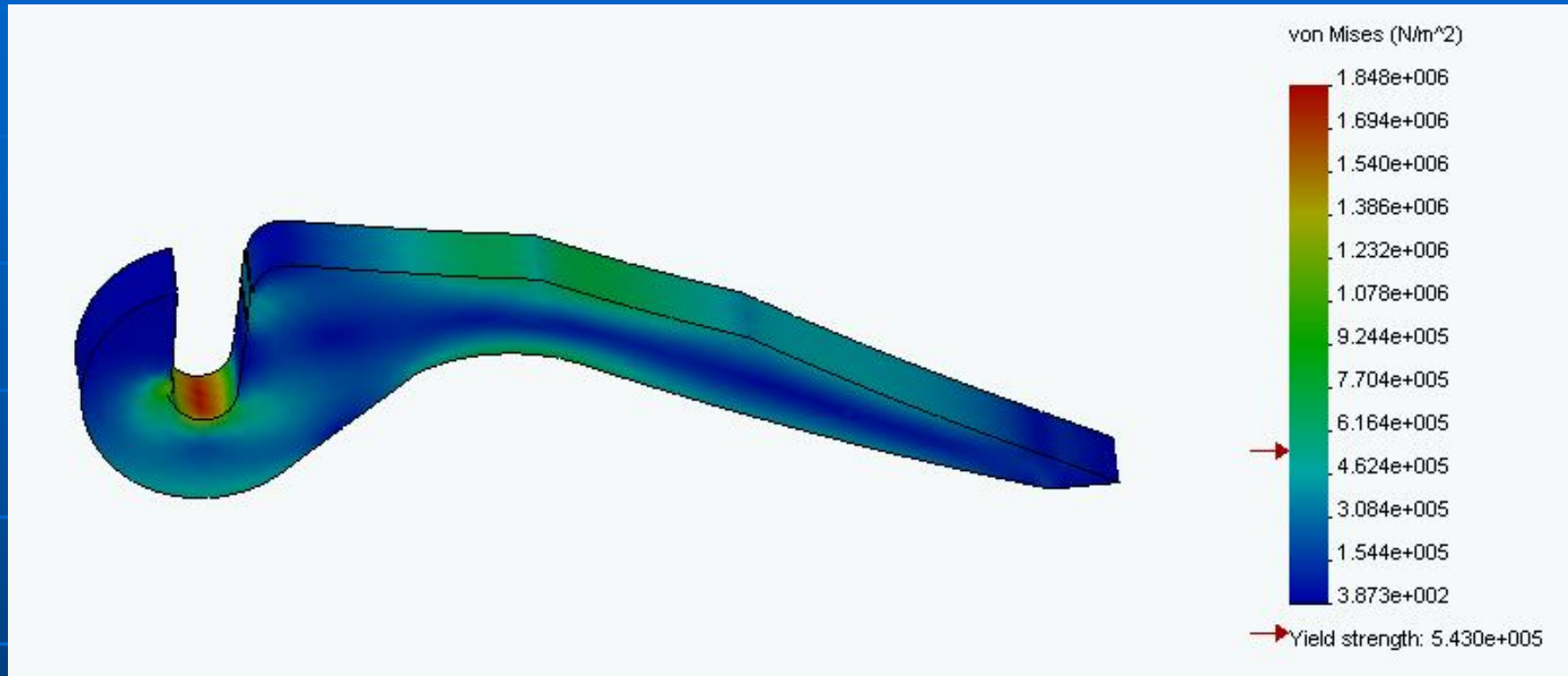
The finite element model was fixed at the contact points. A 50N force was applied at the location of the red arrow in the previous figure.

Mechanics Analysis of Base



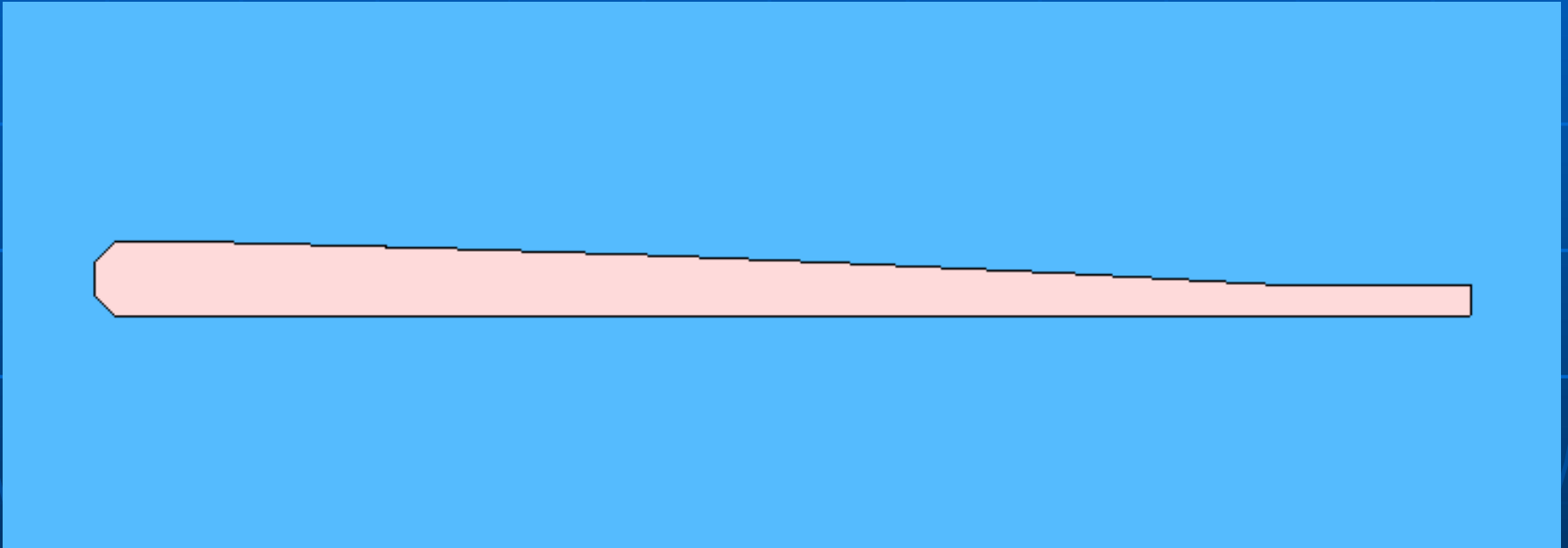
- The black arrows are all the reaction forces to the floor and the arm from the base.
- We assumed that the front of the base (where the arm is connected) could slide forward; this only leaves a reaction force in the vertical direction.

FEM of Base

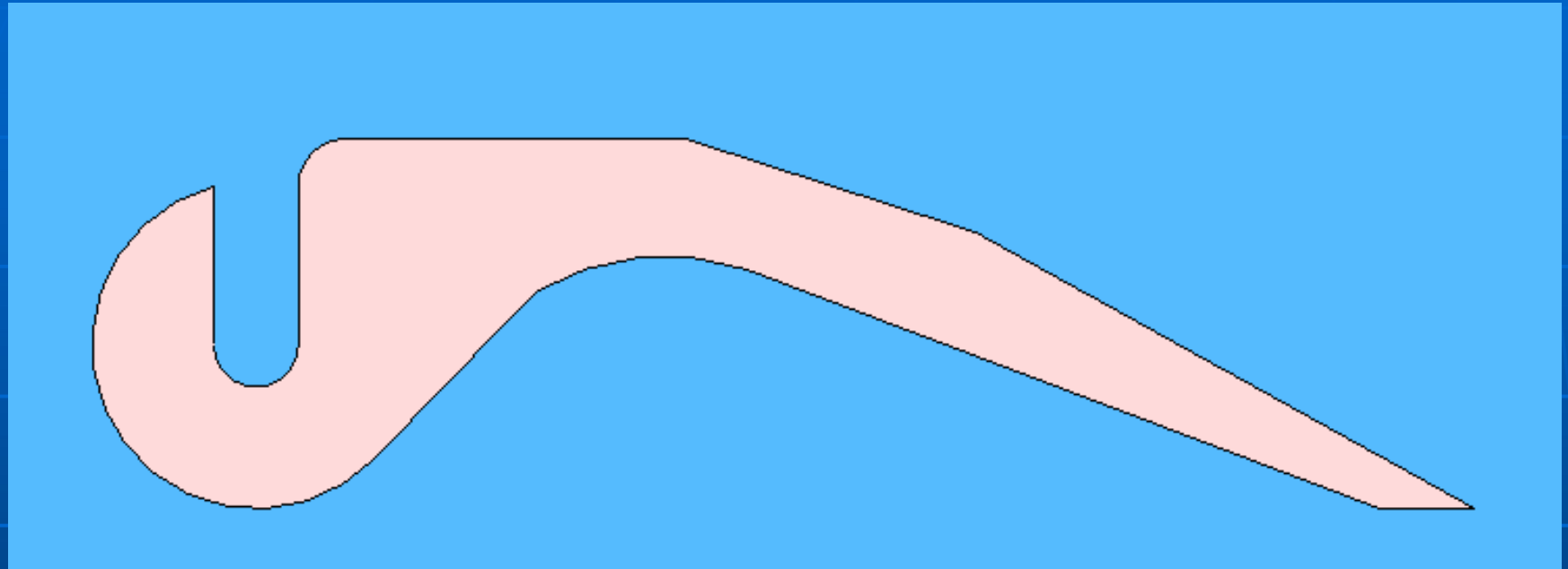


We fixed the trailing end of the catapault and applied a couple at the contact points. The forces used to produce the couple were calculated to be 473.5N.

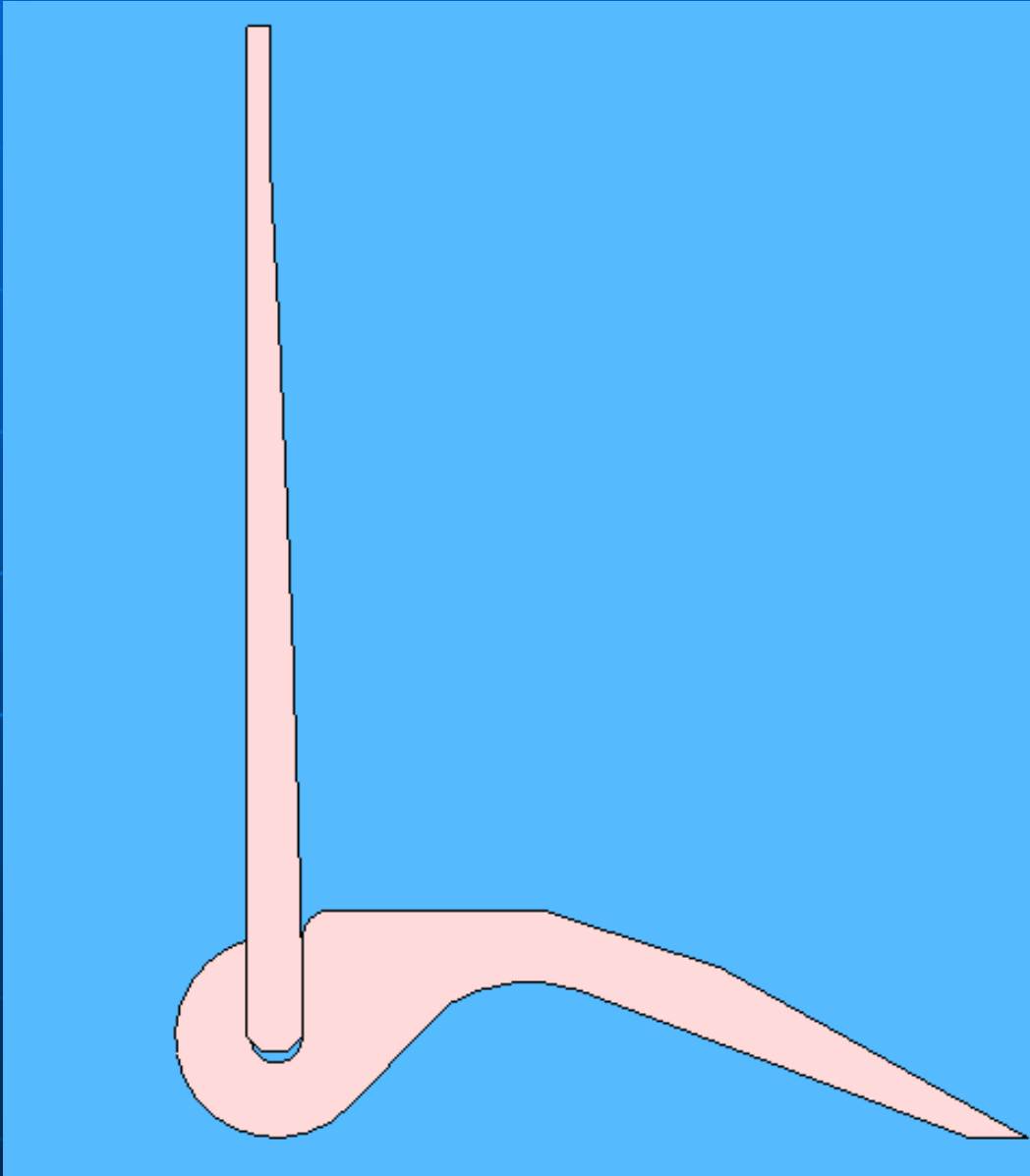
Arm



Base



Assembled Model



Questions?